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Emerging Intraoperative Imaging Modalities to Improve Surgical Precision

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Abstract:	<p>Intraoperative imaging (IOI) is performed to guide delineation and localization of regions of surgical interest. While oncological surgical planning predominantly utilizes computed tomography (CT), magnetic resonance imaging (MRI), and ultrasound (US), intraoperative guidance mainly remains on surgeon interpretation and pathology for confirmation. Over the past decades however, intraoperative guidance has evolved significantly with the emergence of several novel imaging technologies, including fluorescence-, Raman, photoacoustic- and radio-guided approaches. These modalities have demonstrated the potential to further optimize precision in surgical resection and improve clinical outcomes for patients. Not only can these technologies enhance our understanding of the disease, they can also yield large imaging datasets intraoperatively that can be analyzed by deep learning approaches for more rapid and accurate pathological diagnosis. Unfortunately, many of these novel technologies are still under preclinical or early clinical evaluation. Organizations like the Intra-Operative Imaging Study Group of the European Society for Molecular Imaging (ESMI) support interdisciplinary interactions with the aim to improve technical capabilities in the field, an approach that can succeed only if scientists, engineers, and physicians work closely together with industry and regulatory bodies to resolve roadblocks to clinical translation. In this review we provide an overview of a variety of novel IOI technologies, discuss their challenges and present future perspectives on the enormous potential of IOI for oncological surgical navigation.</p>
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<p>Author Comments:</p>	<p>Stanford, April 14th, 2018</p> <p>To: Dr. Gibson Editor-in-chief Molecular Imaging and Biology</p> <p>Dear Dr. Gibson,</p> <p>Please find enclosed a state-of-the-art review entitled 'Emerging Intraoperative Imaging Modalities to Improve Surgical Precision'. This manuscript was written on behalf of the Intra-Operative Study Group of the European Society of Molecular Imaging and in response to the invitation of Prof. Tony Lahoutte and Prof. Bertrand Tavitian to publish a bundle of hot-topic reviews in the June issue of Molecular Imaging and Biology.</p> <p>All authors have reviewed the manuscript and have given final approval. The paper is not under consideration elsewhere.</p> <p>Thank you for your time and kind consideration.</p> <p>Yours Sincerely,</p> <p>Stephan Rogalla & Sophie Hernot Chairs of Intra-Operative Imaging Study Group of ESMI E-mail: srogalla@stanford.edu Tel: 001-650-3025243</p>
<p>Suggested Reviewers:</p>	<p>Christopher H Contag, PhD Professor and Chair, Michigan State University contagch@egr.msu.edu Dr. Contag is a pioneer in the field of optical imaging and molecular imaging in general. He has been past president of WMIS.</p> <p>Alexander L Vahrmeijer, M.D. Ph.D. Professor, Universiteit Leiden A.L.Vahrmeijer@lumc.nl Dr. Vahrmeijer is a physician scientist and an expert in the field of intraoperative imaging. He is head of the research group and former chair and founder of the surgical navigation group at ESMI.</p>

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Emerging Intraoperative Imaging Modalities to Improve Surgical Precision

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4 **Abstract**
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7 Intraoperative imaging (IOI) is performed to guide delineation and localization of regions of
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9 surgical interest. While oncological surgical planning predominantly utilizes computed
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11 tomography (CT), magnetic resonance imaging (MRI), and ultrasound (US), intraoperative
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13 guidance mainly remains on surgeon interpretation and pathology for confirmation. Over the past
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15 decades however, intraoperative guidance has evolved significantly with the emergence of several
16
17 novel imaging technologies, including fluorescence-, Raman, photoacoustic- and radio-guided
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19 approaches. These modalities have demonstrated the potential to further optimize precision in
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21 surgical resection and improve clinical outcomes for patients. Not only can these technologies
22
23 enhance our understanding of the disease, they can also yield large imaging datasets
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25 intraoperatively that can be analyzed by deep learning approaches for more rapid and accurate
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27 pathological diagnosis. Unfortunately, many of these novel technologies are still under preclinical
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29 or early clinical evaluation. Organizations like the Intra-Operative Imaging Study Group of the
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31 European Society for Molecular Imaging (ESMI) support interdisciplinary interactions with the
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35 engineers, and physicians work closely together with industry and regulatory bodies to resolve
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37 roadblocks to clinical translation. In this review we provide an overview of a variety of novel IOI
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39 technologies, discuss their challenges and present future perspectives on the enormous potential
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41 of IOI for oncological surgical navigation.
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53 **Keywords:**
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56 Intraoperative imaging, Surgical navigation, Image-guided Surgery, Fluorescence imaging,
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58 Raman spectrometry, Photoacoustic imaging, Optoacoustic imaging, Thermoacoustic imaging,
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60 Radioguided surgery, Deep learning
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Introduction

For decades, surgical resection has been guided by the naked eye, and despite the surgeon's training, experience, manual dexterity, and meticulous observations, more precise and objective technologies are needed to support surgical procedures [1]. The information required by the surgeon in the operating room (OR) can vary significantly. Oncologic surgeons need to assess tumor margins, the borders between healthy and cancerous tissue and note critical landmarks such as nerves or blood vessels in order to optimize resection of malignant tissue while minimizing harm. Otherwise, in cardiovascular surgery, vulnerable atherosclerotic plaques need to be identified and localized to optimize treatment. Several imaging techniques are applied in the OR with the aim of supporting the surgeon. Ultrasound (US) imaging, for example, is used to re-assess liver tumor location intraoperatively, X-Ray imaging used to confirm catheter positioning, and computed tomography (CT) and magnetic resonance imaging (MRI) are used in neurosurgery for tissue shift correction. However, US suffers from limited contrast imaging capabilities while MRI and CT are challenging to use in the OR due to their size and geometric constraints. Moreover, MRI and CT are costly, cannot yet image in real-time to facilitate rapid intraoperative decision-making, and they present challenges in maintaining a sterile surgical field and may interrupt the workflow.

In recent years, a number of imaging modalities have been successfully utilized for intraoperative guidance, including optical (fluorescence and Raman), acoustic (photoacoustics and radiofrequency (RF)-acoustics), and nuclear imaging-based approaches. These approaches have improved the signal-to-noise ratio of diseased tissue, even in deep-seated regions, thereby augmenting intraoperative identification beyond the limitations of direct visual inspection and palpation. These modalities can be used in standalone fashion to detect intrinsic tissue signals or in conjunction with imaging agents to increase contrast and specificity. Furthermore, they afford synchronous visualization of anatomical and molecular parameters, empowering the surgeon to maximally extract information pertinent to a successful intervention and an improved clinical outcome. However, analyzing the tremendous amount of real-time imaging data acquired by modern IOI technologies is beyond the processing capacity of a human being, and will require the assistance of emerging computational methods, such as deep learning and artificial intelligence.

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4 **Optical imaging techniques**
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6 **Fluorescence-guided surgery**
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9 The main goal of intraoperative imaging (IOI) is to aid in surgical navigation. One approach is to
10 have the specific tissue or lesion of interest literally ‘light up’, for example using fluorescence.
11 Fluorescence imaging is a simple, low-cost, and contact-free method in which fluorophores are
12 excited by an appropriate light source and emitted photons are detected (Fig. 1a). Although the
13 native fluorescence signature of tumors may be different from that of normal tissues [2], the
14 signal’s sensitivity and specificity are often too limited to accurately delineate cancer lesions.
15 Therefore, the development of exogenous agents has become an exciting field of research as an
16 attempt to enhance fluorescent contrast and provide additional functional or molecular
17 information. Fluorescence imaging is highly compatible with the intraoperative setting, as it
18 enables real-time imaging at form factors that can be integrated into the surgical routine, and offers
19 superior sensitivity compared to preoperative imaging or visual inspection and palpation during
20 surgery.[3]
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31 While fluorescence techniques employed in microscopy of cells or naturally transparent organisms
32 (C. elegans, zebrafish etc.) have relied mostly on the use of visible light, near-infrared (NIR)
33 wavelengths in the so-called ‘tissue optical window’ (650-900 nm) are usually preferred for *in vivo*
34 imaging because of lower autofluorescence, deeper tissue penetration (several mm to a cm), and
35 reduced light scattering [4]. Since NIR fluorescence is invisible to the human eye, and to enable
36 detection of small administered doses operating under microdosing conditions, a sensitive
37 photodetector, such as a charge coupled device camera with high spatial and temporal resolution,
38 is indispensable [5-6]. Many fluorescence imaging systems with an integrated light source and
39 camera have already been employed for intraoperative use and several are commercially available
40 [7]. These systems differ in their operational characteristics, i.e. their sensitivity and specificity for
41 certain fluorophores, rejection of ambient light, or ability to image multiple fluorophores
42 simultaneously. Furthermore, depending on the design, they can be applied to open surgeries,
43 minimally-invasive and robotic surgeries, or endoscopic examinations [8]. Wearable display
44 goggles and novel projection strategies have been proposed to obviate standard monitor displays
45 that require the surgeon to divert his gaze from the operative field [9-10].
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4 However, scattering of NIR light by sub-cellular organelles and other microscopic tissue
5 constituents, greatly limits penetration into deep-seated targets and degrades spatial resolution
6 [11]. Fluorescence imaging in the NIR-II window (1000-1700 nm) is currently being investigated
7 in an attempt to increase spatial resolution since tissue exhibits less light scattering at longer
8 wavelengths [12]. Yet, due to the increased attenuation of light in the NIR-II window by lipids and
9 water, the signal-to-noise achieved may be reduced compared to NIR light. Agents that emit in the
10 NIR-II range include single-walled carbon nanotubes and quantum dots, in addition to a few small-
11 molecule-based dyes. These agents are still in preclinical development and their clinical
12 translatability remains to be assessed. Furthermore, advancements in the sensitivity and
13 affordability of detector systems are needed for widespread adoption of NIR-II imaging.
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17 The most commonly used NIR fluorescent agent is indocyanine green (ICG), a clinically approved
18 NIR dye used widely in angiography, perfusion imaging, and more recently sentinel lymph node
19 (SLN) mapping [13]. ICG has also been used for the intraoperative detection of tumors, where it
20 passively accumulates via the enhanced permeability and retention (EPR) effect [14]. Despite its
21 sensitivity, however, ICG has seen limited use due to its lack of specificity. Alternatively, 5-ALA
22 (Gliolan) and its derivate 5-ALA hexyl ester (Hexvix) are two clinically approved pro-drugs used
23 for the visualization of high-grade gliomas and bladder cancer, respectively. They elicit synthesis
24 of protoporphyrin IX, a red-fluorescent protein which accumulates preferentially in malignant
25 tissues. Randomized controlled Phase III clinical trials not only showed that 5-ALA-mediated
26 fluorescence-guidance enabled more effective tumor detection and resection but also improved
27 progression-free survival [15-16].
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31 Most efforts to highlight tumors during surgery over the last decade have focused on improving
32 specificity through receptor-targeted fluorescent agents. These agents specifically recognize
33 membrane-bound biomarkers overexpressed by tumor cells (e.g. EGFR, folate receptor- α , CEA,
34 EpCAM, c-MET, CAIX) or stroma (e.g. VEGF, $\alpha_v\beta_3$, uPAR) [17]. So-called ‘pan-cancer
35 biomarkers’ may be used for detection of multiple cancer types, thereby enabling broad clinical
36 application while avoiding patient preselection.
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40 In 2011, a pioneering first-in-human study demonstrated the feasibility of visualizing tumor burden
41 with FITC-labeled folate during ovarian cancer debulking surgery [18]. Subsequently, several
42 clinical trials, some of which are still ongoing, have investigated the application of fluorescently-
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4 labeled monoclonal antibodies as IOI tracers for a variety of cancer types [8, 19-20]. In many
5 cases, antibodies that are already clinically available as targeted therapeutics are modified with a
6 fluorophore, thereby minimizing regulatory issues associated with the development of a
7 completely new binder. These studies have demonstrated the successful assessment of tumor
8 margins *in situ* during surgery (Fig. 1b) as well as *ex vivo* on excised specimens at both the
9 macroscopic and microscopic level (Fig. 1c) [21-22]. Such back-table fluorescence examination
10 can guide sampling and hasten the pathology report during surgery [23-24]. Nevertheless, further
11 studies are needed to establish objective and standardized criteria for differentiating diseased and
12 healthy tissue, and to demonstrate the impact of fluorescence-guidance on surgical efficacy (clear
13 margin rates, surgery duration, length of hospital stay, complications) and patient outcomes
14 (survival, recurrence-rates, esthetics, and quality of life).
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25 Smaller targeting agents - incorporating peptides, protein scaffolds, or antibody-fragments - with
26 improved pharmacokinetic properties and specificity, have also been developed and are
27 undergoing evaluation [25-29]. For example, fluorescent peptides have been clinically translated
28 that were shown to improve the detection of polyps and neoplastic lesions in humans during an
29 endoscopic examination at early time points [30-31]. Another approach that was shown to be safe
30 and feasible is the use of activatable tracers that become fluorescent upon cleavage of their peptide
31 backbone by tumor-specific enzymes [32]. This strategy is still awaiting thorough clinical
32 investigation.
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40 Finally, during complex surgeries where lesions of interest reside in close proximity to blood
41 vessels and nerves (e.g. in head and neck cancers or prostate cancer), highlighting these vital
42 structures could improve the surgeon's ability to avoid or preserve them. Thus far, direct
43 visualization of nerves with fluorescent agents remains limited to a few preclinically tested nerve-
44 binding fluorophores, fluorescent peptides, and antibodies [33-34]. Color-coding tumors and
45 critical structures for simultaneous viewing will require multi-spectral imaging.
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54 **Raman spectroscopy**

55 As a highly specific and potentially label-free modality, Raman spectroscopy can provide
56 molecular information by analyzing the so-called inelastic scattering of photons upon excitation
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4 (Fig. 1d). When a laser beam interacts with a molecule, photons are scattered and the inelastic
5 scattering can be measured using complex and expensive systems consisting of fiber bundles,
6 lenses, spectrometers, and photomultiplier tubes (PMT). However, as label-free Raman imaging
7 is time consuming, the low signal intensity can be overcome by the use of surface-enhanced Raman
8 nanoparticles (SERS) to amplify the signal [35-36]. One limitation in fluorescence imaging is an
9 often reduced signal *in vivo* compared to *ex vivo* imaging of the same specimen. Furthermore, apart
10 from signal differences due to overlying tissues or camera-to-tissue distances, excitation within
11 cavities (e.g. oral cavity) may be hindered, causing the imaging beam to not ideally excite the
12 fluorophore. This is especially problematic in open field fluorescent systems, but also occurs in
13 very tight and narrow cavities of the human body, where maneuvering may be hindered [37].
14 Raman imaging, on the other hand, does not require the laser beam to hit the target at a specific
15 angle when the signal is enhanced by SERS [38]. In addition, fluorescence imaging is limited in
16 its multiplexing capabilities due to the overlapping spectra of fluorophores, narrowing the number
17 of pathological questions that can be answered in a single procedure. In order to scan multiple
18 disease stages in the same tissue, such as low-grade and high-grade dysplasia, malignancy, and
19 inflammation, multiplexing can be achieved by using disease stage-specific targets with distinct
20 SERS labels. Simultaneously, untargeted SERS of known intensity can be delivered to calibrate
21 the ratiometric image [39]. SERS agents possess a number of features that are attractive for
22 imaging, such as high brightness relative to endogenous Raman signals, having complex and
23 narrow emission spectra that can be used as molecular fingerprints, and affording the capability of
24 multiplexing ten or more parameters. Unlike fluorescence imaging, where autofluorescence
25 contributes significantly to noise, the background in Raman imaging is greatly reduced due to the
26 high specificity of the Raman spectra [40]. SERS agents consist of a gold nanoparticle core coated
27 with a Raman active compound and a silica shell. Although the gold nanoparticles have been
28 shown to persist in organs and tissues long after intravenous injection of SERS agents, no
29 immediate toxic effects have been observed thus far in preclinical testing [41]. For increased
30 specificity, peptides or antibodies can be conjugated to the SERS nanoparticle surface [40] for
31 targeting of cell surface proteins. Due to their size (5-100 nm), SERS agents are not amenable to
32 intracellular targeting [42]. While intravenous administration usually requires several hours for
33 targeting and plasma clearance, topical applications requires very short incubation times and the
34 particles' individual spectral fingerprints can be unmixed immediately [43]. Non-targeted controls
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4 and ratiometric imaging can be used to control for nonspecific pooling and optimization of signal
5 *in vivo* [35]. The utility of Raman imaging for surgical resection has been reported by Liu *et al.*,
6 who topically applied a suspension of five different SERS particles (four targeted and one non-
7 targeted) for 5 minutes on resected xenograft tumor tissue, followed by washing. They were able
8 to clearly distinguish cancer tissue from healthy tissue using this approach and could rule out non-
9 specific binding [39]. Garai *et al.* reported the development, testing, and clinical feasibility of a
10 circumferential scanning Raman micro-endoscopy system that can image the entire colonic lumen.
11 The device has been tested on bench-top colon phantoms, *in vivo* in a porcine model with
12 submucosally injected SERS, and in a human trial in which the topology of the colon was scanned
13 in the absence of SERS [35]. This device can be inserted into the working channel of currently
14 available clinical endoscopes. Since each pixel of a circumferential scan during a controlled
15 retraction of the colonoscope can be mapped, a reconstruction of the topology of the colon wall
16 can be displayed. On top of that image a map showing the location of tumor-targeting SERS
17 nanoparticles displayed in various ways. Location of SERS can be shown as pure spectra, the
18 signal can be shown as a colored patch in a topology phantom or directly overlaid into the white-
19 light endoscopy (Fig. 1e) [35]. This can be used to guide biopsies or removal of residual cancer.
20 In addition, several groups are using Raman for intraoperative imaging or to successfully
21 distinguish between cancer and healthy tissue. Harmsen *et al.* were able to detect tumor cells that
22 were undetectable by common imaging modalities (e.g. CT) in preclinical testing [43]. Thus,
23 powerful and sensitive devices in combination with highly specific SERS agents are rapidly
24 innovating clinical diagnostics and surgical navigation.
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45 **Photoacoustics and thermoacoustic imaging**

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47 To overcome the effects of light scattering in optical imaging of tissues, photoacoustic imaging
48 (also known as optoacoustic imaging) combines the favorable characteristics of both optical and
49 acoustical aspects. The photoacoustic effect is based on pressure transients generated by absorption
50 of pulsed or modulated light [11]. These pressure waveforms experience substantially less
51 scattering than light, as they propagate from absorption sites within the tissue to the tissue
52 boundary. Photoacoustic imaging can be performed over a wide range of depths and resolutions.
53 Similar to optical microscopy, optical-resolution photoacoustic microscopy achieves sub-micron
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4 resolution at sub-mm penetration depths, while acoustic-resolution photoacoustic tomography
5 achieves sub-millimeter resolution at a depth of up to several centimeters [11]. Novel laser
6 technologies and reconstruction schemes allow real-time imaging [44]. The use of multiple
7 wavelengths can allow, in principle, quantification of the various chromophore concentration and
8 thus provide molecular-specific contrast.
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14 Photoacoustic imaging is often combined with ultrasonography whereby the combined approach
15 presents improved anatomical, functional and molecular information. Thus, photoacoustics is
16 ideally suited for integration into the standard surgical workflow. Since certain molecules such as
17 hemoglobin and melanin strongly absorb light, they serve as ideal endogenous contrast agents for
18 photoacoustic imaging of highly vascularized, rich, or pigmented tissues [45]. Quantitative
19 spectral separation of these molecules is challenging due to spectral coloring effects with depth,
20 but it has been recently shown that the unmixing accuracy can be significantly improved by proper
21 algorithmic treatment of data [46]. Anatomical imaging of vascularity combined with functional
22 imaging of hemoglobin levels and oxygen saturation, all performed with photoacoustics, were
23 shown to assist in the detection, staging, and treatment monitoring of various cancers [45],
24 including, but not limited to prostate, thyroid, and breast cancer and melanoma [47-48] as well as
25 for clinical grading for benign diseases, such as inflammatory bowel disease [49-50]. Other clinical
26 applications include real-time measurement of blood flow and tissue temperature. Combined
27 measurements of flow and hemoglobin concentration can be used to assess oxygen consumption
28 and tissue metabolism. These factors are important for determining tumor aggressiveness, tissue
29 healing, and viability [51], as well as for prognostication of several ophthalmic diseases.
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34 Photoacoustic imaging is also an ideal for surgical navigation and biopsy guidance. Several groups
35 have performed phantom studies to assess the feasibility of using acoustic-resolution photoacoustic
36 imaging to accurately locate and identify features of interest, such as blood vessels, nerves, and
37 tendons. These phantom studies mimicked endonasal endoscopic neurosurgeries near the internal
38 carotid arteries [52], the administration of local nerve blocks without causing intraneural damage
39 [53], and teleoperated surgeries using the da Vinci robot [54]. In these approaches, an optical fiber
40 (attached or adjacent to the surgical tool) was used to deliver light into the region of interest while
41 a standard ultrasound probe was placed distally. Both ultrasound and photoacoustic images were
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4 reconstructed with either conventional delay-and-sum beamforming or the short lag spatial
5 coherence technique.
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8 Some preclinical works utilized a probe consisting of optical fibers integrated on top of a medical
9 transducer [55], or a device combining ultrasound, photoacoustic and fluorescence imaging [56].
10 These photoacoustic devices were used for assessing the viability of different tissues and to images
11 cancer in the lymph nodes. Animal experiments have shown the ability of these devices to
12 accurately guide surgery and biopsies to relevant disease foci and to monitor the local delivery of
13 photoacoustic agents.
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16 Other works have investigated a virtual intraoperative surgical photoacoustic microscope [57] used
17 for demonstrating guided needle insertion and retraction. While the resolution achieved here is
18 superior the small field-of-view and penetration depth might limit its clinical use.
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20 Like other imaging modalities, photoacoustics provides limited molecular information in the
21 absence of targeted contrast agents. Consequently, fluorophores are often dually used as
22 photoacoustic agents, of which biocompatible, highly-absorbing NIR dyes are preferred. While
23 only a handful of dyes are currently approved for clinical use, many have been tested preclinically
24 and are expected to receive clinical approval over the next few years. The majority of these
25 exogenous contrast agents are used for tumor delineation. For example, trastuzumab labeled with
26 Black Hole Quencher 3 or fluorescein has been tested by both photoacoustic and fluorescence
27 imaging to assess HER2 overexpression in breast cancer diagnosis, margin assessment, and
28 surgical guidance [58]. Another is the gastrin-releasing peptide receptor targeted photoacoustic
29 agent for prostate cancer imaging [59]. *In vivo* results of both works have shown high resolution
30 and penetration depth, and the ability to provide tomographic views of cancer lesions,
31 demonstrating the advantages of photoacoustics over fluorescence. Finally, Tummers *et al.* have
32 recently addressed the operative management of pancreatic ductal adenocarcinoma (PDAC) by
33 using EGFR-specific cetuximab-IRDye800 as a targeted dual fluorescence and photoacoustics
34 agent [60]. In a first-in-human study in a small cohort of patients undergoing surgical resection for
35 pancreatic cancer. Fluorescence imaging and photoacoustic imaging successfully delineated the
36 tumor region compared to its surroundings during surgery.
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57 In conclusion, photoacoustics has immense potential for surgical guidance because it is portable,
58 can provide real-time imaging at high resolution and penetration depth uses both endogenous and
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4 exogenous contrast agents, and uses nonionizing radiation. Multiple systems and contrast agents
5 have begun to emerge in recent years, and much current work is focused on *ex vivo* and phantom
6 studies to characterize these systems.
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10 Another emerging medical imaging technique that could prove valuable in surgical navigation is
11 thermoacoustic imaging (also called radio-frequency (RF)-acoustics) [61]. Thermoacoustics is
12 mechanistically very similar to photoacoustics, but far-infrared light to ultra-high frequency radio
13 waves are used for excitation instead of NIR light. Since tissue is mostly transparent at these
14 wavelengths and scattering is minimal, a few-fold increase in imaging depth is usually achieved
15 compared to photoacoustics. However, the low tissue absorption, particularly in the longer
16 wavelength regime, results in low endogenous contrast, which explains why this modality has
17 received little attention thus far. However, thermoacoustic contrast stems from differences in
18 dielectric properties, which have been harnessed in developing some interesting exogenous
19 contrast agents [62]. The most common agents are magnetic or superparamagnetic nanoparticles
20 (such as Fe₃O₄), some of which are already FDA approved for clinical use. Another interesting
21 class of agents includes polar molecules like sucrose or ionic solutions like saline [63], which can
22 be encapsulated into nanostructures and functionalized to target various molecular targets.
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37 **Nuclear imaging modalities**

38 Nuclear imaging modalities, single photon emission computed tomography (SPECT) and positron
39 emission tomography [64], are non-invasive whole-body imaging technologies, valued for their
40 sensitivity and limitless depth of penetration. 2D scintigraphy and 3D SPECT employ nuclides
41 like Technetium-99m (^{99m}Tc, t_{1/2} 6 h) and Indium-111 (¹¹¹In, t_{1/2} 2.8 days), that emit gamma
42 photons of varying energies, which are then detected by gamma cameras. The sensitivity of SPECT
43 (10⁻¹⁰-10⁻¹¹ mol/L) is further surpassed by PET (10⁻¹¹-10⁻¹² mol/L), which additionally yields
44 quantitative information [3]. PET isotopes like Fluorine-18 (¹⁸F, t_{1/2} 1.8 h) and Iodine-124 (¹²⁴I,
45 t_{1/2} 100.3 h) decay by emitting positrons (beta particulate emissions) that travel short distances
46 before colliding with electrons in the surrounding tissues. This results in the production and
47 coincident detection of two gamma rays (of 511 KeV), 180 degrees apart.
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57 Pre-operative nuclear imaging has a strong record in providing surgeons with diagnostic
58 information, therapy follow-up as well as providing a road map to plan the most optimal surgical
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4 approach towards resection. For example, intravenously administered ^{18}F -Fluorodeoxyglucose (^{18}F -
5 FDG), the most widely used clinical PET tracer enables measurement of glucose transport and
6 glycolysis, which are up-regulated across a range of malignancies. Moreover, scintigraphy and
7 SPECT imaging are performed routinely prior to intra-operative assessment of radiotracer
8 localization using radio-guided surgery (RGS). For intraoperative localization of gamma emitting
9 tracers in real-time, first conceived in 1949, RGS typically uses a hand-held gamma radio-
10 detection probe in conjunction with SPECT isotopes that are injected directly into or next to
11 suspected lesions prior to surgery (Fig. 1h). RGS has become standard-of-care in a defined set of
12 surgical procedures. These include SLN biopsy (SLNB) in breast, head and neck cancer and
13 malignant melanoma and radioguided occult (impalpable) lesion localization (ROLL) in breast
14 cancer, providing surgeons with valuable real-time information regarding the location of SLN
15 for further pathological evaluation and extent of disease respectively. $^{99\text{m}}\text{Tc}$ in various colloidal
16 forms (e.g. $^{99\text{m}}\text{Tc}$ -sulfur colloid) has been most commonly used in the clinic for SLNB [65],
17 favored for its wide availability and the relative low absorbed dose associated with its use. Meta-
18 analysis of numerous clinical trials have shown that RGS used in conjunction with optical dyes
19 leads to higher rates of SLN detection (>91%) vs when blue dyes used on their own (~83%) and
20 also reduces false negatives [66].
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36 Another interesting application of RGS is the use of ^{125}I -seeds to mark small, impalpable lesions,
37 prior to surgery in patients with breast cancer and as an alternative to wire-guided localization.
38 Intraoperative, gamma tracing of these ^{125}I -seeds allow the surgeon to precisely localize and excise
39 the lesions. Advantageously, this approach can be used in conjunction with injection of colloidal
40 $^{99\text{m}}\text{Tc}$ for SLN identification due to the unique gamma energy signatures of both isotopes [67]. The
41 use of ^{125}I -seeds provides a more comfortable alternative to patients in comparison to the wire-
42 guided approach and reduces conflicts between radiologist and surgeons.
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50 The lack of image documentation in RGS with gamma probes however, fueled the development
51 of hand-held and portable small gamma cameras (Fig. 1i), such as the Sentinella S102® system.
52 These can cover larger fields of view (FOV), can increase surgical accuracy and are increasingly
53 being included in the RGS workflow. Vidal-Sicart *et al.* reported the higher detection of SLN in
54 patients with melanoma, breast and gynecologic cancers with a portable γ -camera used in
55 conjunction with a hand-held γ -probe (95%) versus when the latter was used on its own (75%)
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4 [68]. The advent of freehand SPECT systems such as the declipse@SPECT that enable 3D
5 visualization of radioactivity overlaid on a real-time video of the surgical field, provide virtual
6 or augmented reality information with the potential to further improve surgical navigation [69].
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10 Though RGS using PET tracers is not as well established, it has been evaluated in the clinic to
11 guide resection, assess lymph node metastasis in a range of malignancies, and locoregional nodal
12 status for initial staging of breast cancer [64, 70]. Most of these studies have used ^{18}F -FDG,
13 typically administered a few hours prior to surgery. A dedicated PET high-energy gamma probe,
14 designed specifically to detect the 511 keV photons, has been evaluated in numerous clinical
15 studies. However, a recent study by Orsaria *et al.* concluded that hand-held PET gamma probe-
16 guided surgery with ^{18}F -FDG performed poorly in evaluating axillary lymph nodes due to high
17 background gamma levels from local and distant parts of the body [64]. PET tracers have also been
18 evaluated with a hand-held positron detection probe, although the short range of beta emissions
19 (typically 2-3 mm in soft tissue for ^{18}F -labeled agents) precludes the detection of deep-seated
20 lesions, detection of beta emissions provides greater specificity (higher TBRs) in the localization
21 of superficial tumor deposits. However, their use is limited by a small FOV, low resolution, and
22 long acquisition times. In 2013, Singh *et al.* reported a prototype of a handheld beta-imaging
23 intraoperative probe to allow visual mapping of beta emissions. This was evaluated *ex vivo* on
24 rabbit tumor tissue, and was reported to have high spatial resolution and sensitivity, but is yet to
25 be evaluated *in vivo* and in the clinic [71]. Ongoing hardware and software development for these
26 PET-based RGS technologies is expected to enhance spatial resolution and improve disease
27 detection. The success of these studies, however, has been limited not only by current probe design,
28 but also by limitations in the commonly used ^{18}F -FDG tracer itself, including its inability to
29 distinguish inflammation from malignant processes, high accumulation in the urinary tract due to
30 excretion, and high background in glucose-avid tissues such as the brain and heart. Additionally,
31 the ability of the hand-held probes to detect lesions is variable and dependent on the ^{18}F -FDG
32 avidity of the tumor. In this regard, other radiotracers can overcome limitations of ^{18}F -FDG.
33 Advantageously, numerous small-molecule and immunoPET tracers are in preclinical
34 development in addition to the many that are already FDA approved.
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57 An interesting feature of positron-emitting PET tracers is that they generate Cerenkov
58 luminescence, produced when a charged β -particle traverses a dielectric medium at a speed greater
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4 than the velocity of light in the same medium. The feasibility of clinical Cerenkov imaging was
5 firstly demonstrated by Thorek et al. for ^{18}F -FDG and Spinelli et al. using 131-Iodine [72-73].
6 Because Cerenkov is intrinsic to the PET tracer, it circumvents the need for an external excitation
7 light source, avoids the depth limitations of excitation light, and uses compact imaging equipment.
8 Although in its infancy, preclinical and early ex vivo clinical studies have demonstrated
9 Cerenkov's utility in the identification of tumor (margins) and metastatic lymph nodes [74] or are
10 currently underway (NCT02666079). Dependent on the detection of low levels of blue-weighted
11 light, Cerenkov is susceptible to absorption and scatter and therefore lacks sensitivity and
12 resolution, making it more suitable for visualization of superficial structures.
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21 RGS could benefit significantly from a multimodal approach, combining for example the detection
22 radioisotopes with fluorescence imaging. The in-depth and sensitive detection capabilities of
23 emitted gamma-rays could synergize well with the more superficial, but higher resolution
24 fluorescent signals. This concept was first illustrated using a self-assembled complex of $^{99\text{m}}\text{Tc}$ -
25 albumin radiocolloids and ICG for SLN biopsies [75-76] and is also being applied to the radical
26 resection of renal cell carcinoma with a dual-labeled (^{111}In and IRdye800CW) Girentuximab
27 monoclonal antibody [77] (NCT02497599). Several groups are working to generate true hybrid
28 detection modalities for intra-operative use, e.g. combining fluorescence and gamma tracing [78].
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38 **Deep learning**

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40 One technology that could fundamentally change how diagnostic images are analyzed and read
41 over the coming years is deep learning. Deep learning is a type of machine learning that has the
42 potential to not only improve diagnostic accuracy but significantly reduce the workload and
43 backlog faced by physicians and radiologists. A particularly effective deep learning model for
44 image classification is the convolutional neural network (CNN), a type of artificial neural network,
45 which is inspired by the hierarchical connectivity of neurons in the brain [79-81]. Previously, most
46 machine learning algorithms require images to undergo significant pre-processing prior to analysis
47 and classification. For example, a radiologist or surgeon would first need to contour, or segment,
48 organs or lesions of interest in an image by hand and annotate objects of interest based on shape,
49 texture, or other distinguishing characteristics. By contrast, a CNN can directly use an unannotated
50 raw image as an input and classify the image (for example, for the presence or absence of a lesion)
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4 based on comparison with a large dataset of pre-classified images [79-81]. Deep learning for
5 computer-aided diagnosis has been demonstrated on images taken in the pre-operative setting: for
6 example, to detect lung nodules in chest X-rays [82-84], differentiate malignant from benign lung
7 lesions on CT [85], detect masses and microcalcifications in mammography [86-89], and segment
8 brain tumors in MRI imaging [90]. CNN models have also demonstrated utility in minor
9 interventional procedures, such as in determining whether a peripherally inserted central catheter
10 (PICC) has been positioned correctly based on chest X-rays [91]. However, as these algorithms
11 become more efficient and processing times rapidly decrease, the prospect of using deep learning
12 to guide the surgeon intraoperatively in real-time is already on the horizon. For example, a recent
13 study trained a CNN model to detect colorectal polyps in colonoscopy images[92]. The training
14 and validation sets contained a total of 8641 images: half contained polyps of all sizes and
15 morphologies, and half contained no polyps. The classification had an accuracy of 91% and an
16 area under the curve (AUC) of 0.96. Because their CNN model can process 170 images per second,
17 it has the potential to identify polyps in real-time from the live video stream during the colonoscopy
18 procedure. In another study, a CNN model was trained on 7894 confocal laser microendoscopy
19 (CLE) [21] images from 116 video sequences of the oral cavity (both benign and cancerous
20 regions) in 12 patients with oral squamous cell carcinoma, and was found to have an accuracy of
21 88.3% and an AUC of 0.96 [93]. By subdividing the images into smaller patches, the investigators
22 were able to reduce the complexity of the computation, which can enable faster processing with
23 the eventual goal of a CLE system that can accurately identify high-risk regions in real-time for
24 immediate biopsy and histologic evaluation. Similar deep learning technologies could be
25 envisioned for real-time lesion identification in more complex surgical procedures. Furthermore,
26 CNN models have been used that can recognize and potentially even track the surgical instrument
27 being used (grasper, hook, scissors) during laparoscopic procedures as well as the type of surgical
28 action (blunt dissection, cutting, suturing) being carried out [94-96]. One can foresee the use of
29 such algorithms for training assistive or semi-autonomous robots in picking up the appropriate
30 surgical instrument and correctly performing a set of surgical tasks. In addition, deep learning
31 algorithms that can analyze video in real-time could be combined with augmented reality surgical
32 navigation systems and used in robot-assisted surgeries to alert or even resist the surgeon when an
33 impending action could compromise critical blood vessels or anatomic structures.

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4 **Conclusion and Future Perspectives**
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6 Over the last few decades, a wide variety of new technologies have emerged for intraoperative
7 guidance that mostly relies on molecular imaging principles. Because of their higher sensitivity,
8 higher resolution, and real-time capabilities, they have the potential to overcome the current
9 limitations of state-of-the-art modalities such as CT, MRI and US. The ease of use and current
10 availability of tracers, either already clinically approved or close to clinical translation, places
11 fluorescence and radio-guided approaches as the most advanced. Nevertheless, although we can
12 be highly enthusiastic about the first results, large multicentric clinical trials still need to
13 demonstrate their impact on surgical outcome and patient survival. The respective shortcomings
14 of optical and nuclear approaches can be overcome with further advancements towards hybrid
15 modalities, e.g. nuclear/fluorescence or photoacoustics/fluorescence, or with other experimental
16 technologies. However, the latter still need to prove their utility in the clinic and the specific use-
17 cases for which they can be of added-value remain to be identified. In the future, it can be expected
18 that deep learning approaches will be used more frequently with intraoperative imaging to
19 automatize detection of tissues of interest and further improve signal-to-noise ratio and superior
20 recognition of structures, thus supporting the surgeon tremendously.
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41 exchange within the society and beyond.
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47 **Author contributions**
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49 All authors wrote, reviewed and approved the manuscript.
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44 Figures

45 **Figure 1:** Principle and representative images obtained with distinct intraoperative imaging
46 approaches: fluorescence imaging (a-e), photoacoustic imaging (d-e), Raman-spectrometry (f-g)
47 and radio-guided surgery (h-i). Of note, the light source and detector for optical and photoacoustic
48 imaging approaches are most often integrated in a single device. (b) **Fluorescence imaging** can
49 be used to assess tumor margin in situ or (c) ex vivo on excised specimens (reproduced with
50 permission from [21] and [23]) (e) **Raman imaging** can be displayed in pure spectra
51 demonstrating the presence of Raman particles or displayed as a map either within a phantom tube
52 mimicking the colon or directly inside the white-light camera view. (g) Combined **Photoacoustic**
53 and ultrasonography can highlight molecular contrast overlaid on the anatomical view to guide
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5 surgery or biopsy. Contrast is either endogenous (Hemoglobin) or based on absorbing or
6 fluorescent agents. A triple modality hand held probe is used to probe Melanoma metastasis in a
7 Rabbit's lymph node. (h) **Radioguided surgery** can be performed using hand-held gamma or beta
8 probes to detect the presence of SPECT or PET based radiotracer for localization of sentinel lymph
9 nodes and metastasis. (i) The use of hand-held probes can be supplemented with intra-operative
10 gamma cameras as reported by Vidal-Sicart et al. [68]: pre-operative SPECT-CT of patient with
11 malignant melanoma injected with 99mTc-nanocolloid and an intraoperative portable gamma
12 camera being used (i, top panel, L to R). Gamma camera images of the surgical field before and
13 after resection (i, bottom panel, L to R).
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